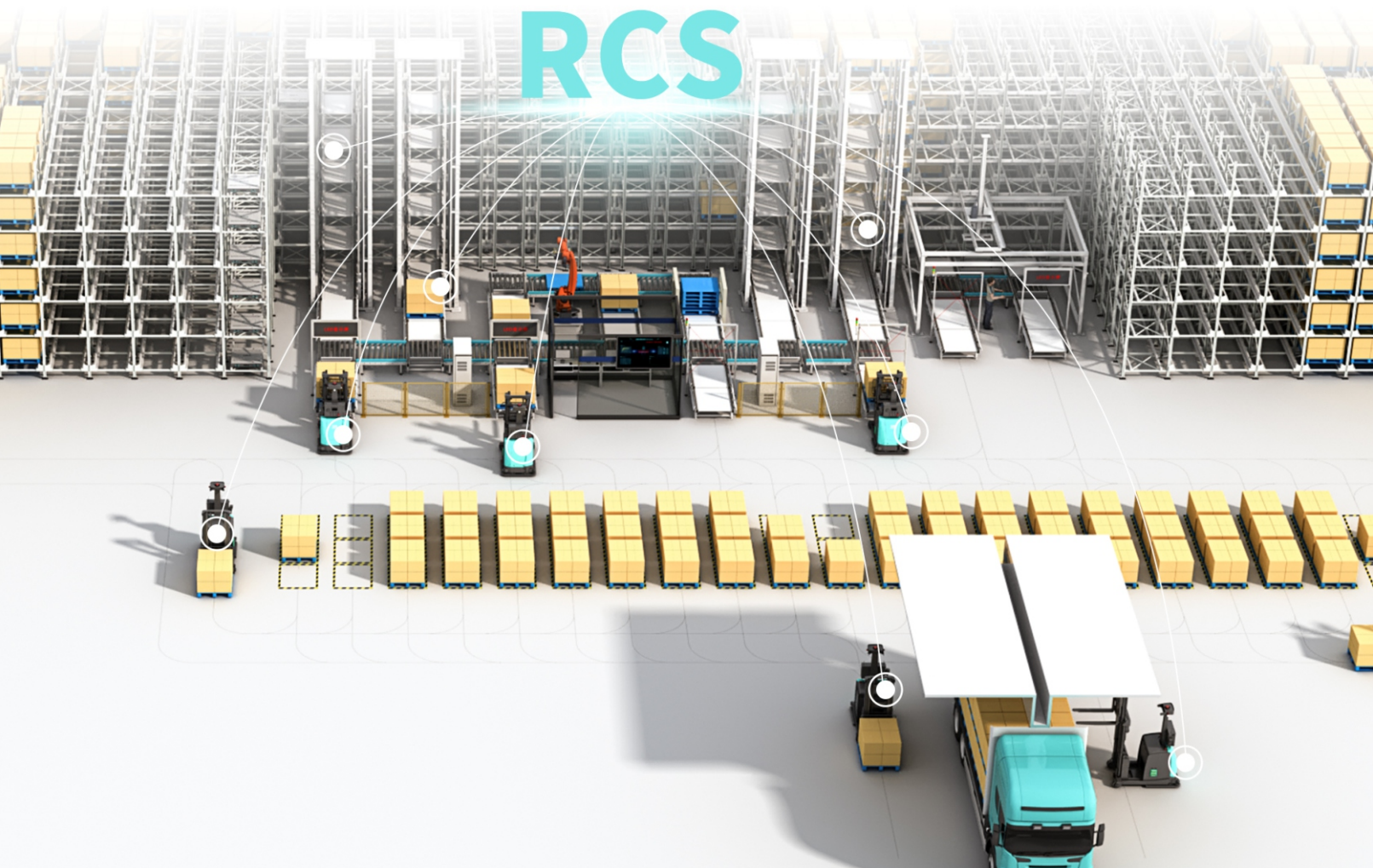


Multiway Robotics



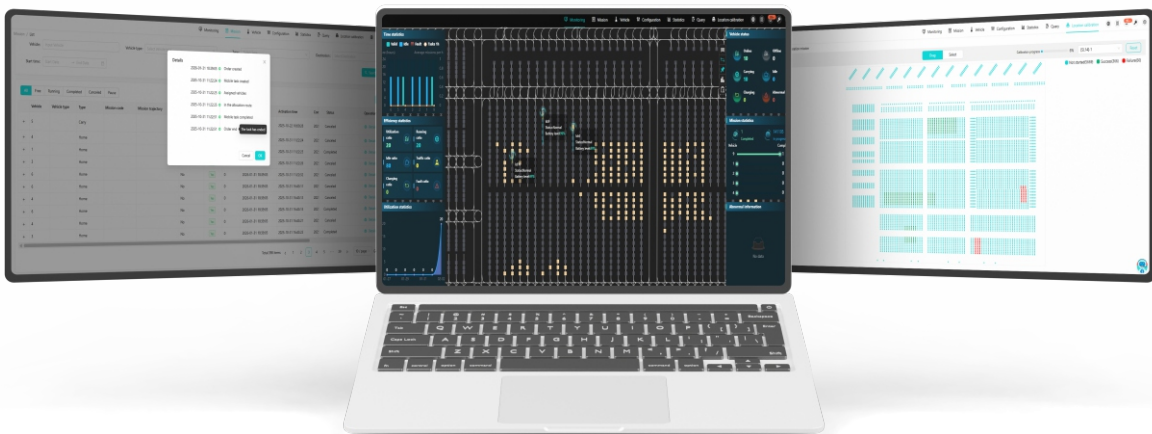
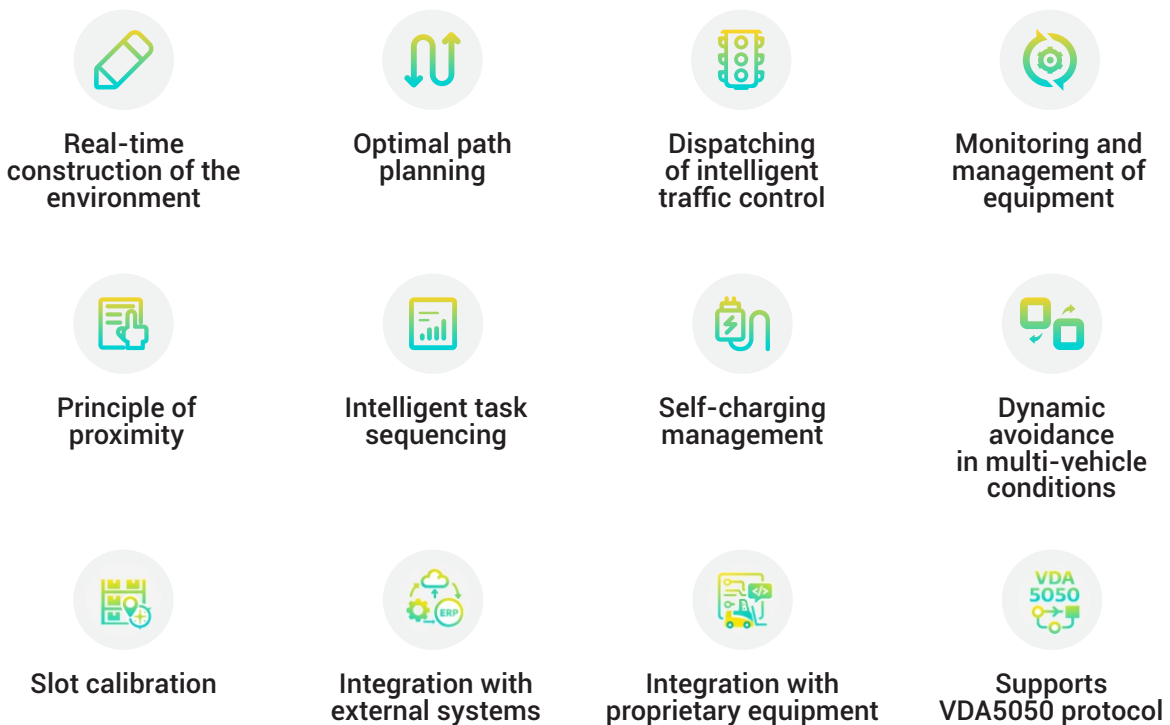
Dispatching System RCS

Multiway Robotics Co., Ltd.

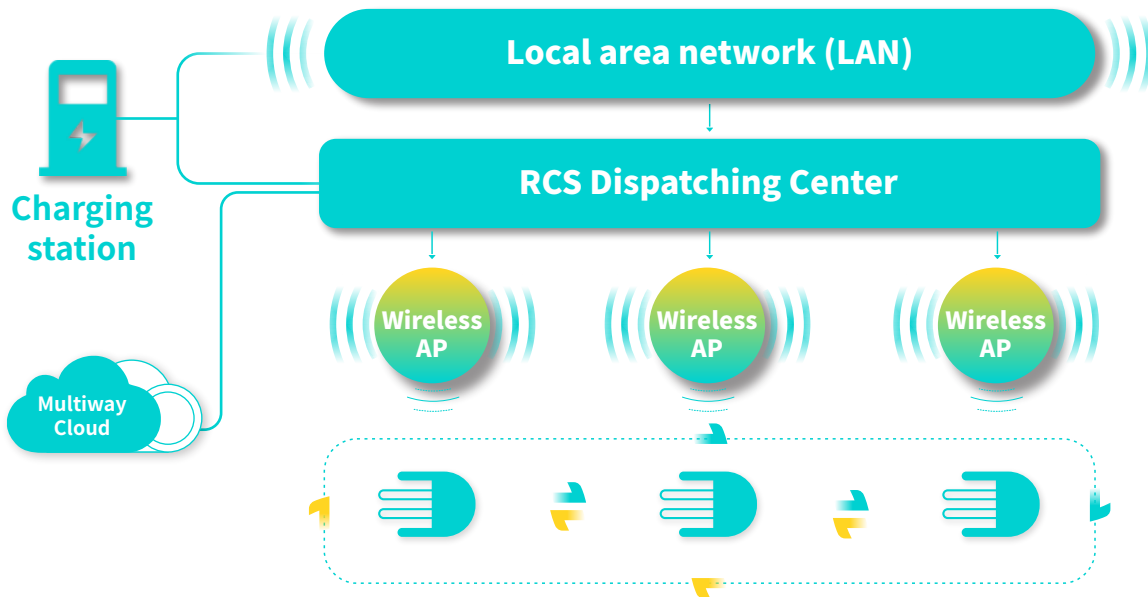
Introduction to RCS System

The Multiway Robotics Dispatching System can simultaneously **support the cooperative operation of hundreds of vehicles of different models on the same site**. It can quickly design optimal routes and optimal navigation route planning, thus completing tasks in the shortest time and ensuring the highest efficiency.

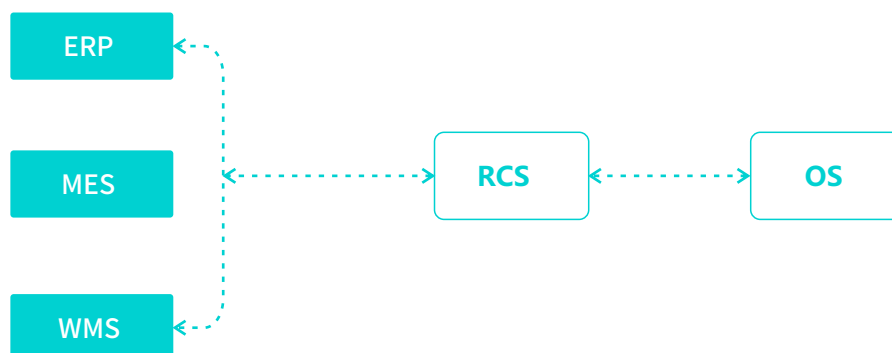
Currently, Multiway Robotics Dispatching System has been deployed in **1000+** real projects in the fields of **automotive, food, pharmaceutical distribution, new energy, cold chain, etc.**, with more than a hundred units deployed at the site of several leading enterprise customers.



Network Architecture



System Interfacing Logic



System Function

Dynamic monitoring



Web-based system information access and remote monitoring are available



Real-time display of operational maps (Support 3D digital twin)



Real-time display of vehicle position, status, battery level, etc.



Real-time display of vehicle task statistics



Real-time display of vehicle anomalies/alerts



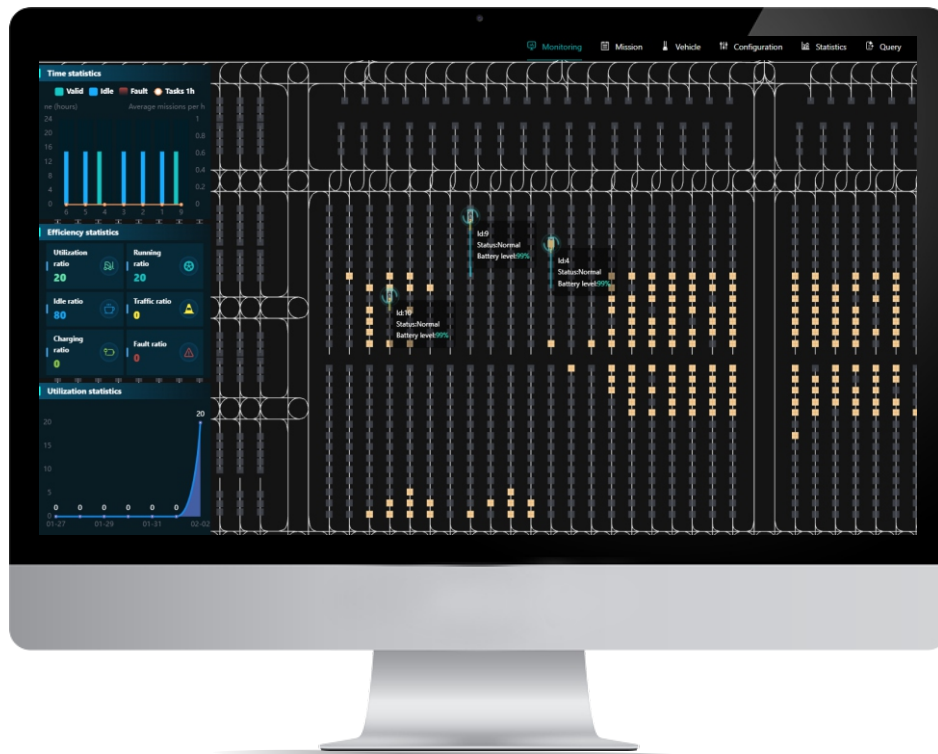
Supports quick dispatch of templated tasks



Support for configuring parameters in the back-stage

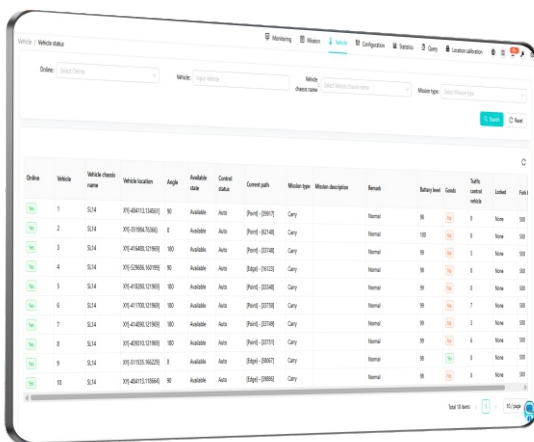
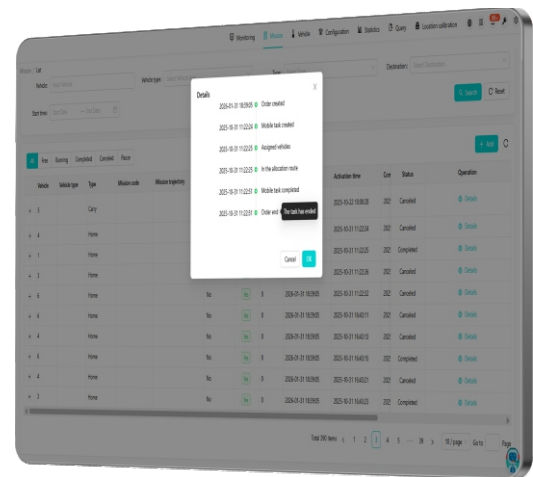


Different users or user groups can set operation privileges



Task management

- Monitor task execution status in real time
- Create tasks to assign vehicles to transport goods to a target point
- Create recurring tasks
- Manually cancel and complete tasks in the management task status
- Supports creating templated tasks

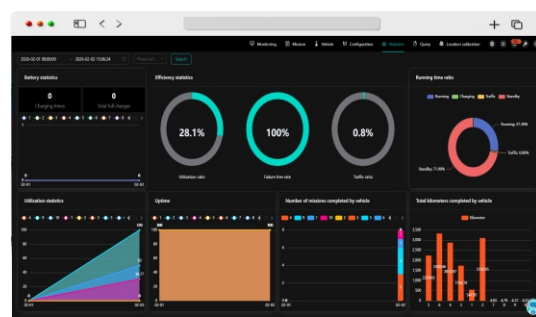


Vehicle management

- Monitor vehicle operating status in real time
- Configure vehicle information
- Configure simulation vehicles to simulate the operation of real vehicles
- Supports area-based configuration to enable vehicles to execute tasks by designated zones

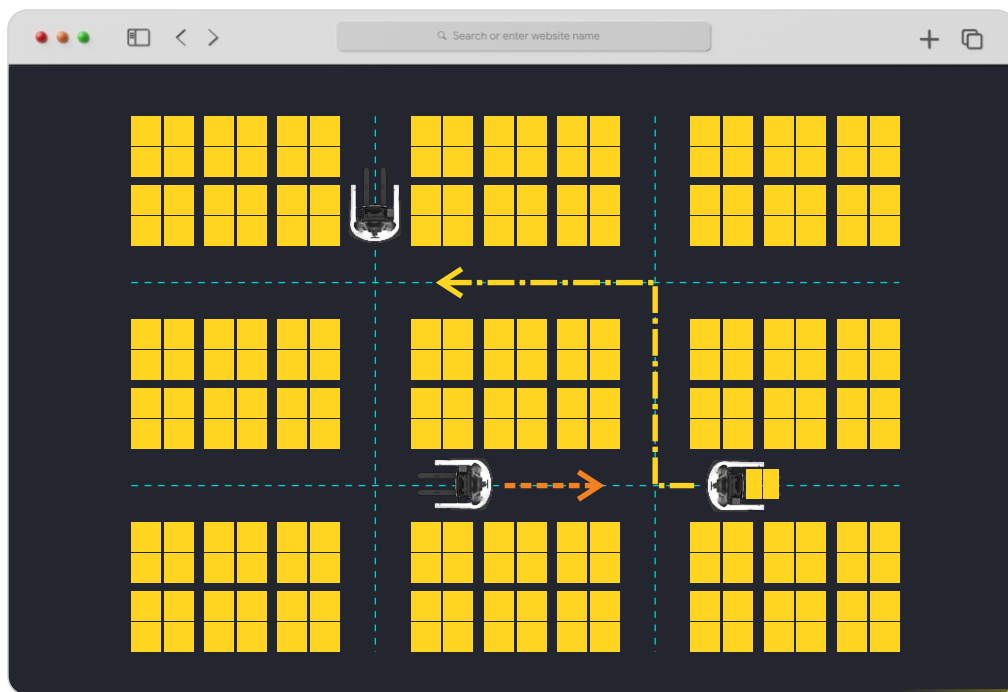
Report statistics

- Record running track, traffic control time, failure rate, etc.
- Record running tasks and automatically generate task logs
- Data analysis (efficiency, mileage, utilization, etc.), support for graphs and data export
- Report system failures, generate events, and query logs



Traffic control

- Optimize routes for traffic control in real time
- Adjust the vehicle running profile to reduce traffic pipes and avoid collisions in real time
- According to the robot meeting/following status, task priority, adjust the traffic control issuing mechanism in real time
- According to road conditions, adjust and dynamically avoid in real time
- Traffic control handling of multiple cars on different floors calling the same elevator at the same time
- Vehicle-road collaboration is available
- Supports obstacle avoidance at the system level
- Supports intelligent vehicle traffic management



Traffic control mechanism



Space
collision
detection



Control of
route
issuance



Block
group
protection



Restrictions
on roadway
operations



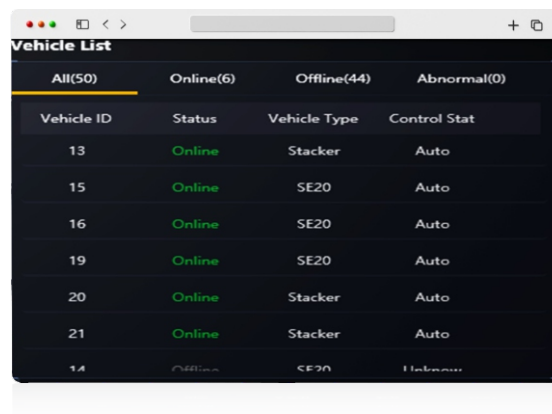
Event
interaction
mechanism



Dynamic
avoidance
algorithm

Equipment management

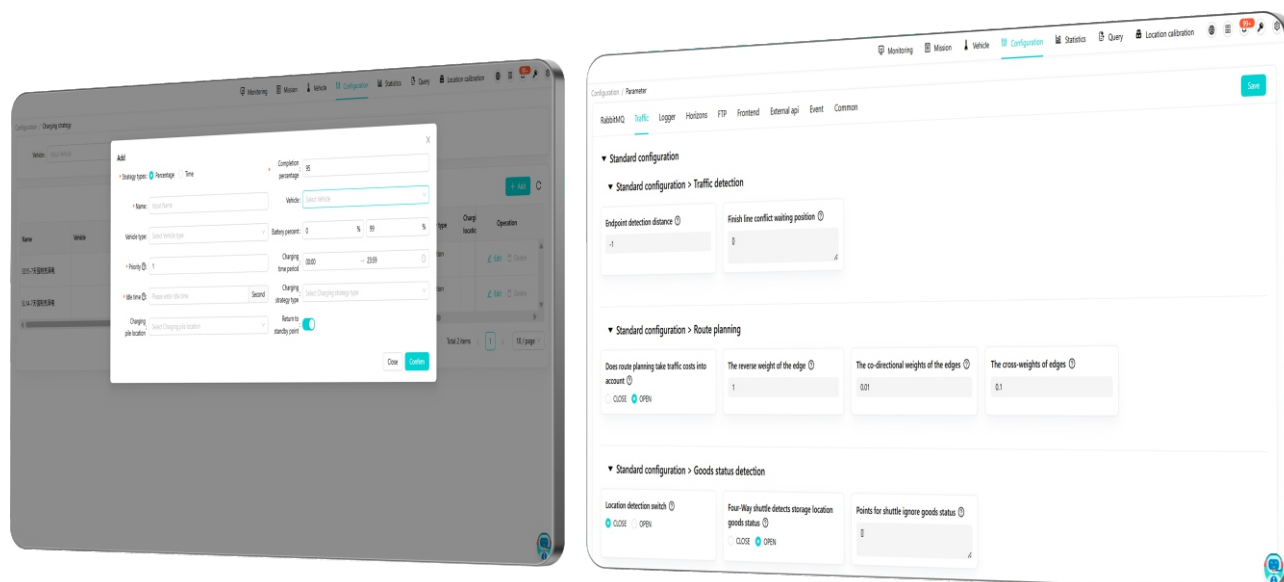
- Self-check the communication status of robot components in real time
- Monitor multiple robot batteries for low battery warning and recharging in real time
- Monitor robot position, obstacle avoidance, motion and other information in real time
- Real-time monitor the communication status of various modules docking in the system
- Remote one-touch parking is available
- Remote OTA upgrade without manual intervention
- Supports integration with proprietary devices (e.g., automatic doors, elevators, etc.)



Vehicle List			
All(50) Online(6) Offline(44) Abnormal(0)			
Vehicle ID	Status	Vehicle Type	Control Stat
13	Online	Stacker	Auto
15	Online	SE20	Auto
16	Online	SE20	Auto
19	Online	SE20	Auto
20	Online	Stacker	Auto
21	Online	Stacker	Auto
14	Offline	SE20	Unknown

System configuration

- Event configuration: configure notification, interaction events with WCS
- Charging configuration: configure automatic vehicle charging strategy
- Standby point configuration: configure the vehicle to automatically return to the designated standby point
- Map configuration: map upload, map activation
- Model configuration: model information configuration
- Station configuration: charging point, standby point, storage point, etc.



Multiway Robotics

Multiway Robotics, a leading intelligent intralogistics solution provider, is dedicated to improve intralogistics efficiency, ensure work safety and reduce labor operational cost.

Global Presence: The headquarters is located in Shenzhen, China, with production facilities in Zhejiang Wuzhen. Multiway has also established subsidiaries in the United States, Germany, Japan, South Korea, and more, extending business, operations, and services to 40+ countries and regions worldwide.

Our Expertise: Focusing on advanced robotics and AI technology, Multiway Robotics is committed to delivering cutting-edge Smart Intralogistics Solution to our customers. Multiway offers a comprehensive, integrated innovation delivery platform and solutions, ranging from core sensors and algorithms to self-developed unmanned forklifts and upper-level control systems. Hardware products include a full range of unmanned forklifts and four-way shuttle, while software systems encompass WMS, RCS, WCS, on-site management systems, and various visual solutions.

Software WMS, RCS, WCS, Multiway Horizons, Simulation

Hardware: AGV forklifts, AGV Tugger, AMR & Four-way Shuttle

After successfully delivering numerous benchmark projects in industries such as factories, warehousing, and logistics, Multiway has become a trusted and ongoing collaborative partner for many industry-leading customers.

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